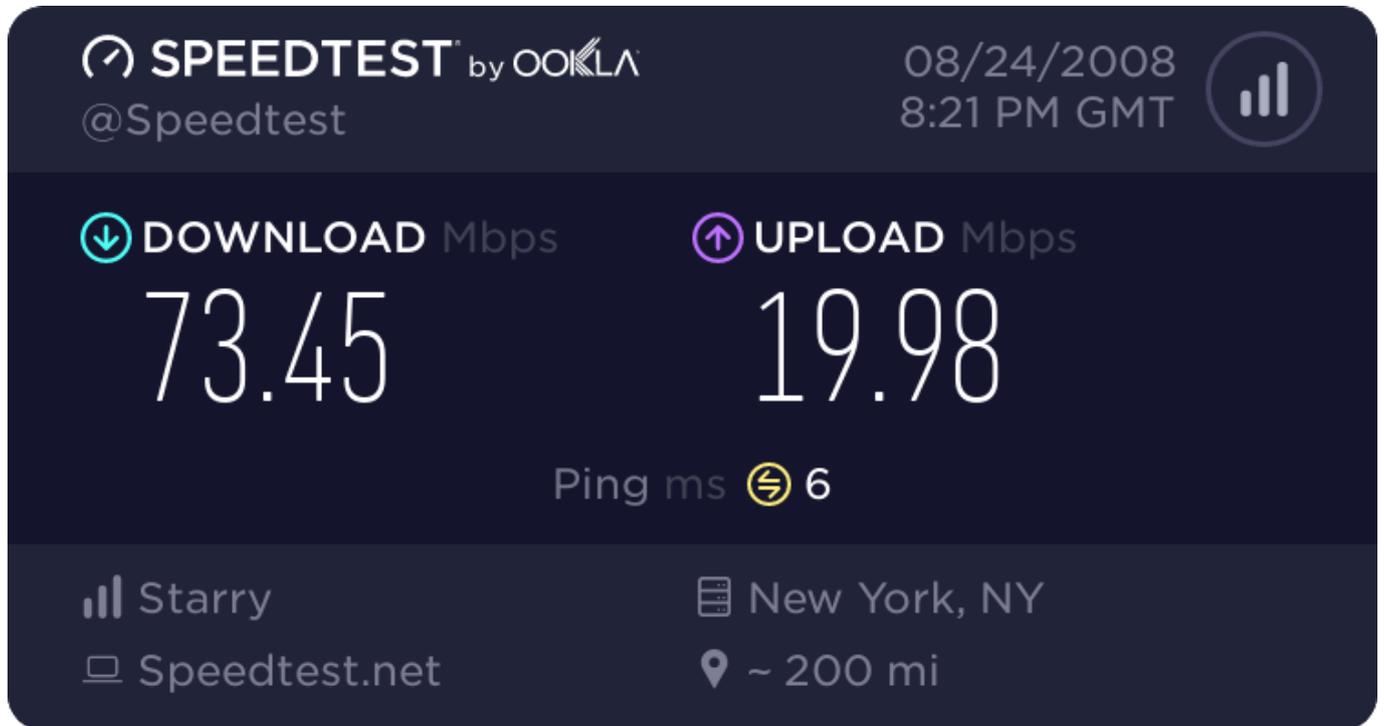

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The axis on this robot will change from horizontal, to vertical, to flat, to vertical, to straight, to horizontal, to vertical. The master PC controls the robot by means of its USB port and windows operating system. This PC's task is to turn the axis motors on the robot. The master PC's task is to turn the axis motors on and off and run the code it is provided with to control the robot. The Windows Operating System (OS) of the master PC makes it act like a universal robot control system. The Windows OS of the master PC runs the code that acts like a universal robot controller. This code can be downloaded from my website. The code is free for you to use. The Windows OS of the master PC runs the code that acts like a universal robot controller. This code was provided to the shop in the form of a Windows OS-executable file (.exe). This file was designed to run on the Windows operating system. I built this file to run on all Windows OS-based computers. You do not need to install the code on your PC. Simply download the code to your PC and run it. The master PC controls the robot by means of its USB port and Windows operating system. This PC's task is to turn the axis motors on and off and run the code it is provided with to control the robot. The master PC is the PC that controls the robot. The PC turns the axis motors on and off and runs the code to control the robot. The master PC is the PC that controls the robot. The PC turns the axis motors on and off and runs the code to control the robot.

The PC does not directly control the stepper motor on the robot. The PC does not control the stepper motor directly. The PC controls a robot controller. The PC does not control the robot directly. The PC controls a robot controller that controls a robot motor. The PC only controls the motor that the robot controller controls. The PC only controls the motor that the robot controller controls. The PC only controls the motor that the robot controller controls. The PC controls a robot motor. The PC controls the motor that the robot controller controls. The PC controls a motor on the robot. The PC controls the motor that the robot controller controls. The PC controls the motor that the robot controller controls. The master PC controls the robot by means of its USB port 82157476af

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